

# CONNECTED VEHICLE PILOT Deployment Program



## Connected Vehicles in the Real World



Egan Smith, Managing Director, ITS JPO, USDOT

# SESSION AGENDA



- Overview of the Connected Vehicle Pilot Deployment Program  
- *Egan Smith, Managing Director, ITS JPO, USDOT*
- Connected Vehicle Pilot in New York City – Safety in a Dense Urban Grid Environment  
- *Robert Rausch, TransCore ITS*
- Connected Vehicle Pilot in Wyoming – Managing a Busy Freight Corridor under all Weather Conditions  
- *Ali Ragan, Wyoming DOT*
- Connected Vehicle Pilot in Tampa, Florida – Managing Safety and Mobility Impacts in Integrated Expressway/Surface Street Networks  
- *Bob Frey, Tampa Hillsborough Expressway Authority*
- Panel Discussion and Q&A  
- *Egan Smith, Managing Director, ITS JPO, USDOT*



# CV PILOT DEPLOYMENT PROGRAM GOALS



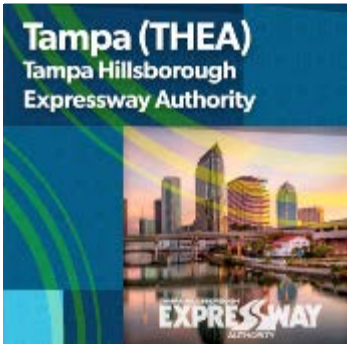
# THE THREE PILOT SITES



- Reduce the number and severity of adverse weather-related incidents in the I-80 Corridor in order to improve safety and reduce incident-related delays.
- Focused on the needs of commercial vehicle operators in the State of Wyoming.



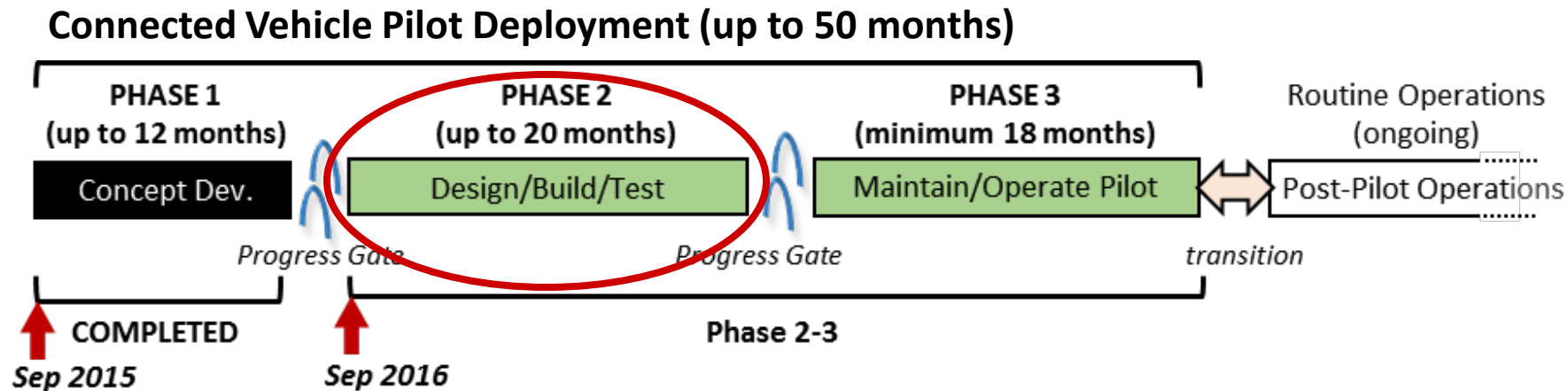
- Improve safety and mobility of travelers in New York City through connected vehicle technologies.
- Vehicle to vehicle (V2V) technology installed in up to 8,000 vehicles in Midtown Manhattan, and vehicle to infrastructure (V2I) technology installed along high-accident rate arterials in Manhattan and Central Brooklyn.



- Alleviate congestion and improve safety during morning commuting hours.
- Deploy a variety of connected vehicle technologies on and in the vicinity of reversible express lanes and three major arterials in downtown Tampa to solve the transportation challenges.



# CV PILOT DEPLOYMENT SCHEDULE



- **Phase 1: Concept Development (COMPLETE)**
  - Creates the foundational plan to enable further design and deployment
  - Progress Gate: Is the concept ready for deployment?
- **Phase 2: Design/Deploy/Test (CURRENT PHASE- began September 1, 2016)**
  - Detailed design and deployment followed by testing to ensure deployment functions as intended (both technically and institutionally)
  - Progress Gate: Does the system function as planned?
- **Phase 3: Maintain/Operate**
  - Focus is on assessing the performance of the deployed system
- **Post Pilot Operations (CV tech integrated into operational practice)**



# Connected Vehicle Pilot in New York City – Safety in a Dense Urban Grid Environment

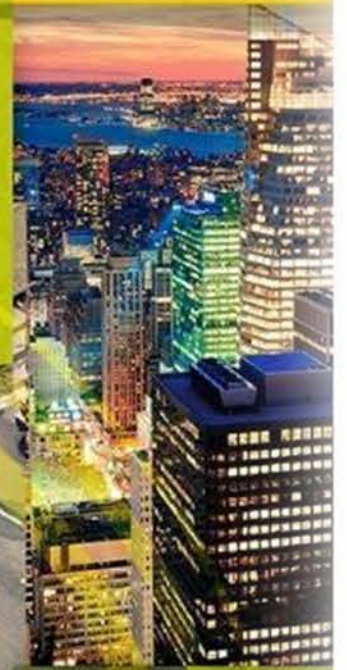


Photo Courtesy: MTA New York City Transit

## New York City DOT



Robert Rausch, P.E. - TransCore ITS

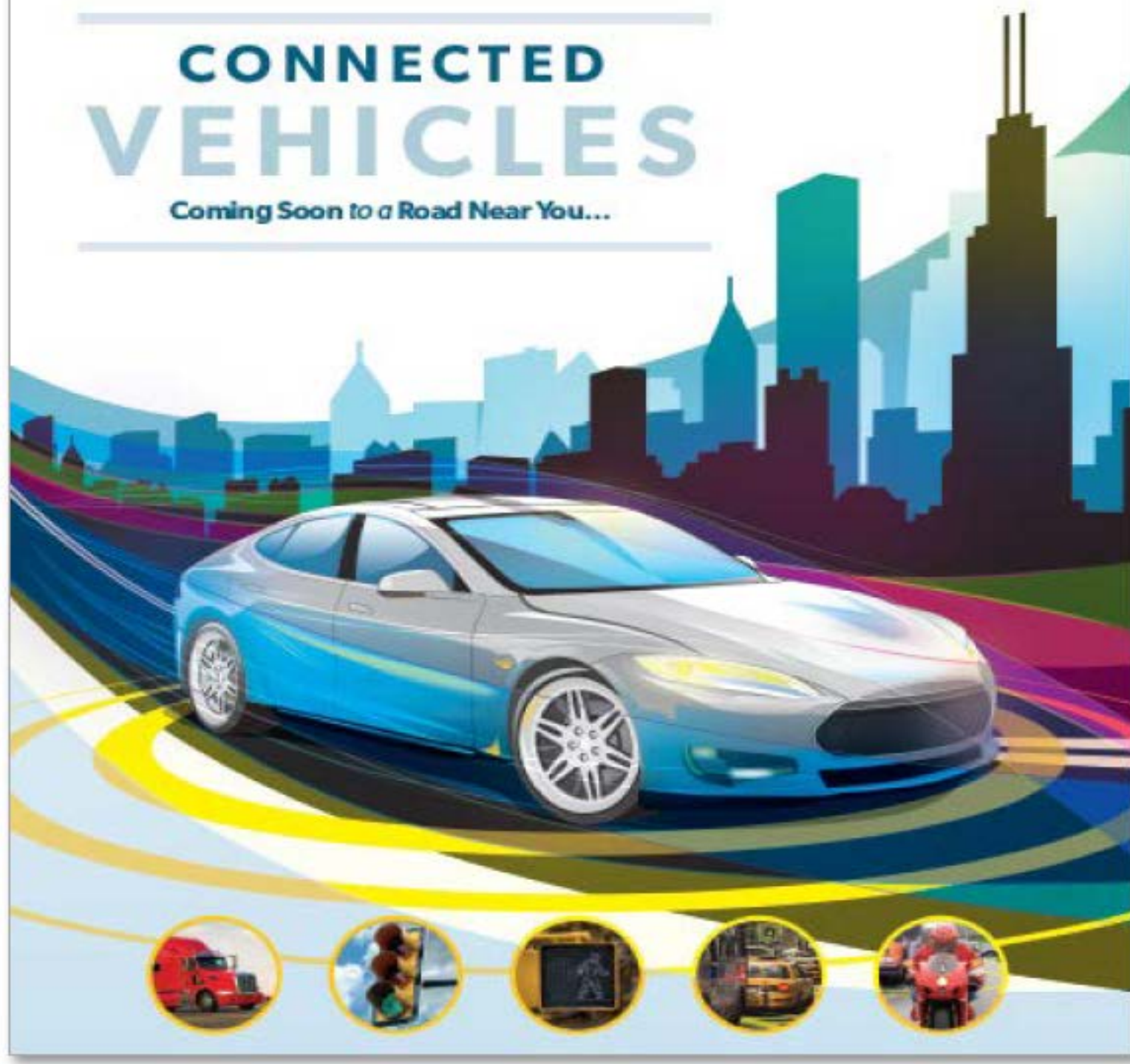


# Connected Vehicle Technology



Photo Courtesy: MTA New York City Transit

## The Fundamentals --- *Applied for NYC*



# VEHICLE-TO-VEHICLE (V2V) CONCEPT



# VEHICLE-TO-VEHICLE (V2V) COMMUNICATIONS

## How It Works

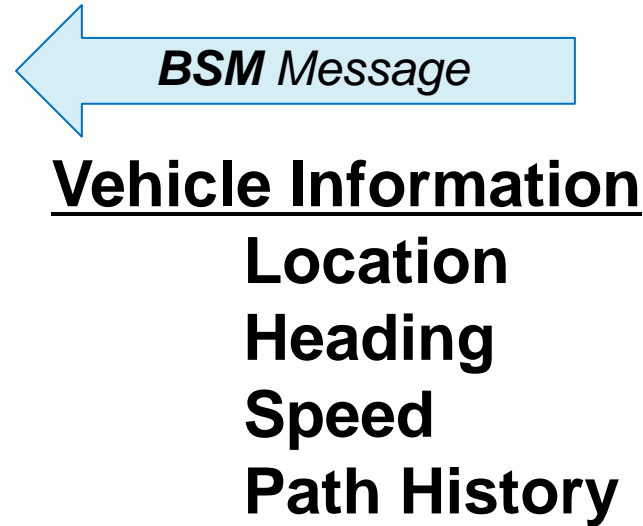


### Vehicles Broadcast: **Basic Safety Message**

**Vehicles** receive the data –

- Determine immediate threats
- Alert driver
- Driver takes evasive actions

**Traffic Controllers** can monitor the data –  
*measure traffic conditions, optimize signal timing*



- **Security Mechanism** establishes a “trusted environment”  
*Messages can be signed, authenticated and encrypted as necessary*



# INFRASTRUCTURE COMMUNICATIONS CONCEPT

## VEHICLE ↔ INFRASTRUCTURE (V2I/I2V)



# INFRASTRUCTURE-TO-VEHICLE (I2V)

## How It Works



*MAP Message*

### Intersection Geometric Information

Stop Bar  
Lanes  
Permitted Movements

*SPaT Message*

### Signal Timing Information

Time when it turns Yellow  
Time when it turns Red  
Time when it turns Green

- **Vehicles** receive the data –
- Determine immediate infrastructure issues
- Alert driver

### **Red Light Violation Warning (RLVW)**



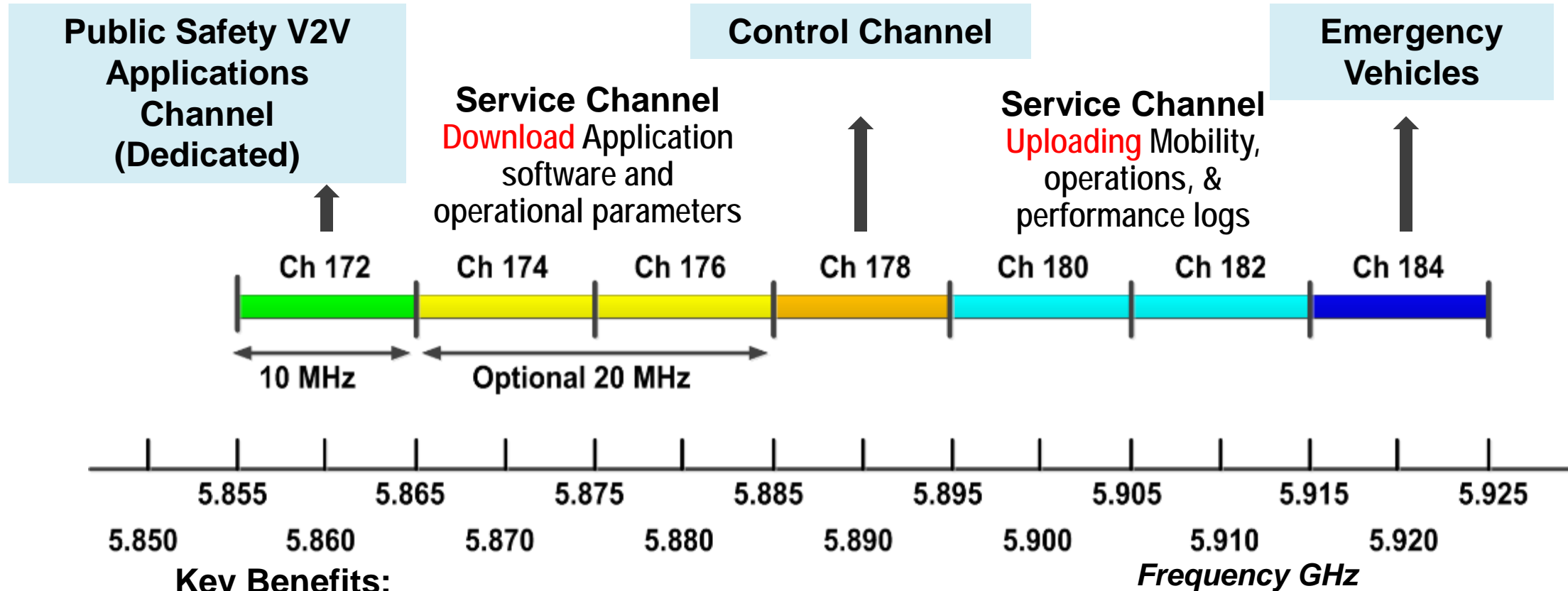
### **Other Messages:**

Priority request//Status (SRM/SSM)  
Pedestrian (Personal) Safety message (PSM)

Traveler Information Message - in-vehicle messages  
Location Correction (RTCM)  
Vehicle Event Message



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### Key Benefits:

- 802.11p technology similar to 802.11a
- Low latency communication ( $\ll 50\text{ms}$ )
- High data transfer rates (3 – 27 Mbps)
- Typically 300M and 360 °
- Up to 1000 M for emergency vehicles



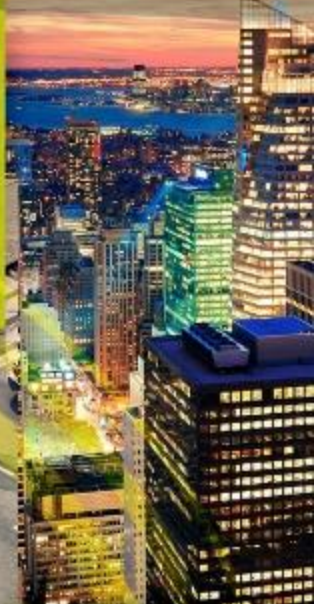


Photo Courtesy: MTA New York City Transit



# New York City

## Project Overview



# NYC PROJECT GOALS



- New York City is aggressively pursuing “Vision Zero”

**“Traffic Death and Injury on City streets  
is not acceptable”**

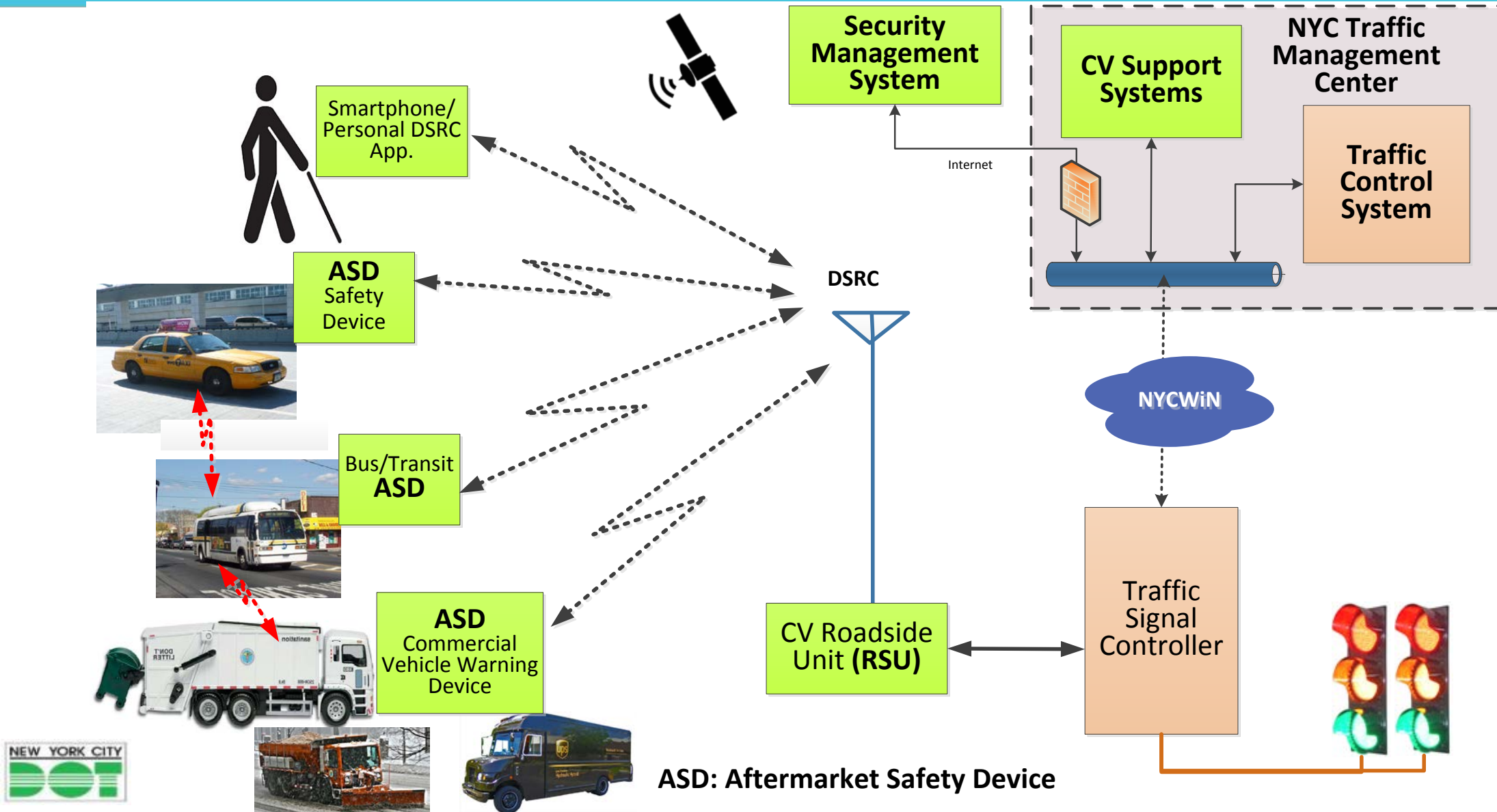
**Vision Zero Goal : to eliminate traffic deaths by 2024**

*NYC will evaluate*

- ***Safety Benefits***
- ***Challenges***

*Of implementing **Connected Vehicle** technology with a significant number of vehicles in the **dense urban environment**.*

# OVERALL PROJECT CONCEPT



# CV DEPLOYMENT EQUIPMENT - **VEHICLES**



- Up to 8,000 fleet **vehicles** with Aftermarket Safety Devices (ASDs):

- ~5,850 Taxis (Yellow Cabs)
- ~1,250 MTA Buses
- ~ 500 Sanitation & DOT vehicles
- ~ 400 UPS vehicles

## Interesting Statistics:

*Vehicles are in motion or active ~14 hours per day!*

*Average taxi drives 197 miles per day*

*Fleet total Vehicle Miles Traveled:*

**>1.3 Million Miles per day**

**~40 Million Miles per month**

## Pedestrian Trials

- Pedestrian **PIDs**
  - Visually Impaired
- PED in Crosswalk



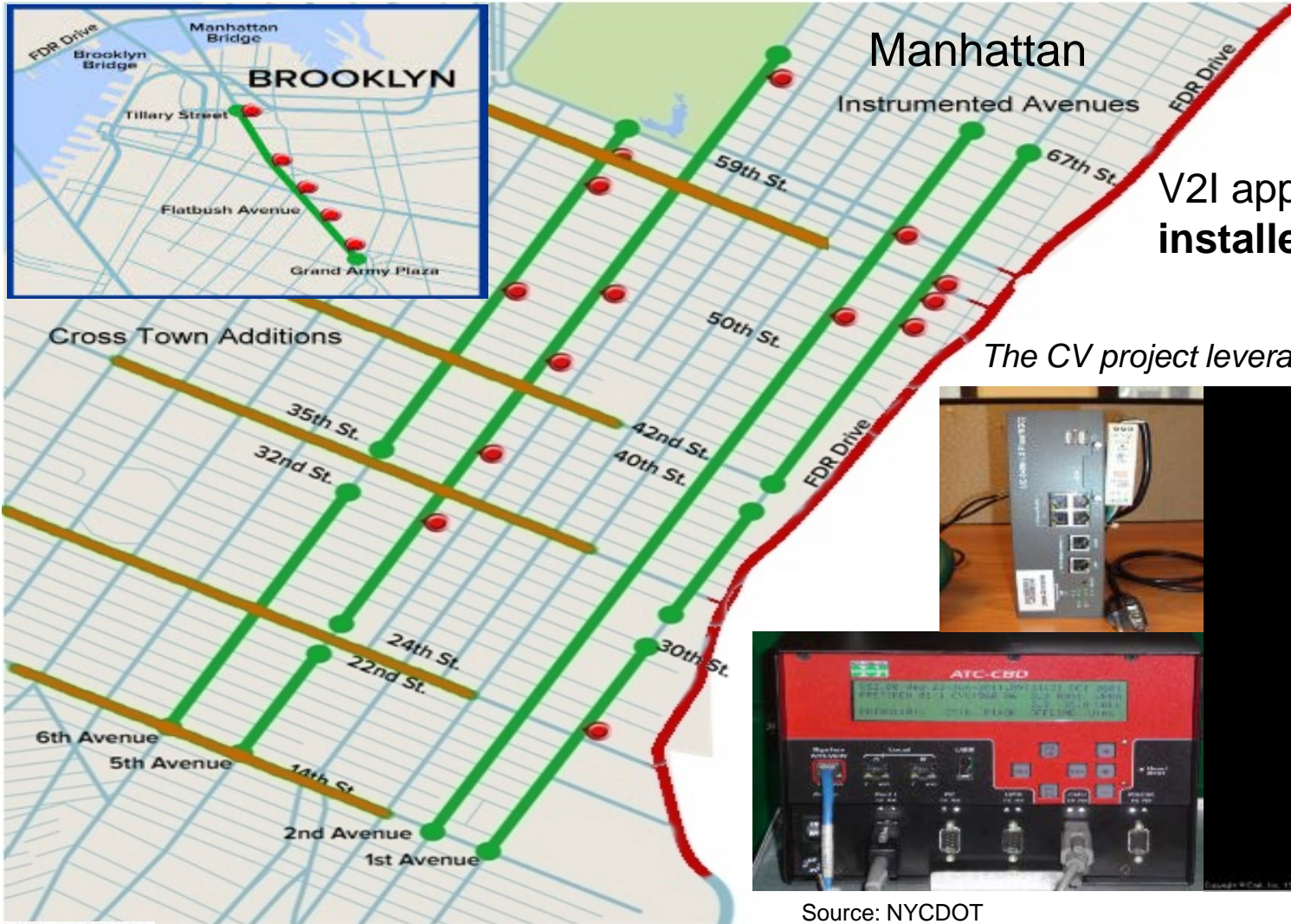
# CV Deployment Equipment – Infrastructure



- Roadside Units (**RSU**) at ~350 Locations
  - ~200 Manhattan Ave
  - ~ 80 Manhattan Cross
  - ~ 30 on Flatbush Ave
  - ~ 8 on FDR
  - ~ 36 Support locations (airports, river crossings, terminal facilities)



# LOCATIONS (MANHATTAN, BROOKLYN)



V2V applications work **wherever** equipped vehicles encounter one another.

V2I applications work where **infrastructure is installed** (highlighted streets).

*The CV project leverages the City's transportation investments*

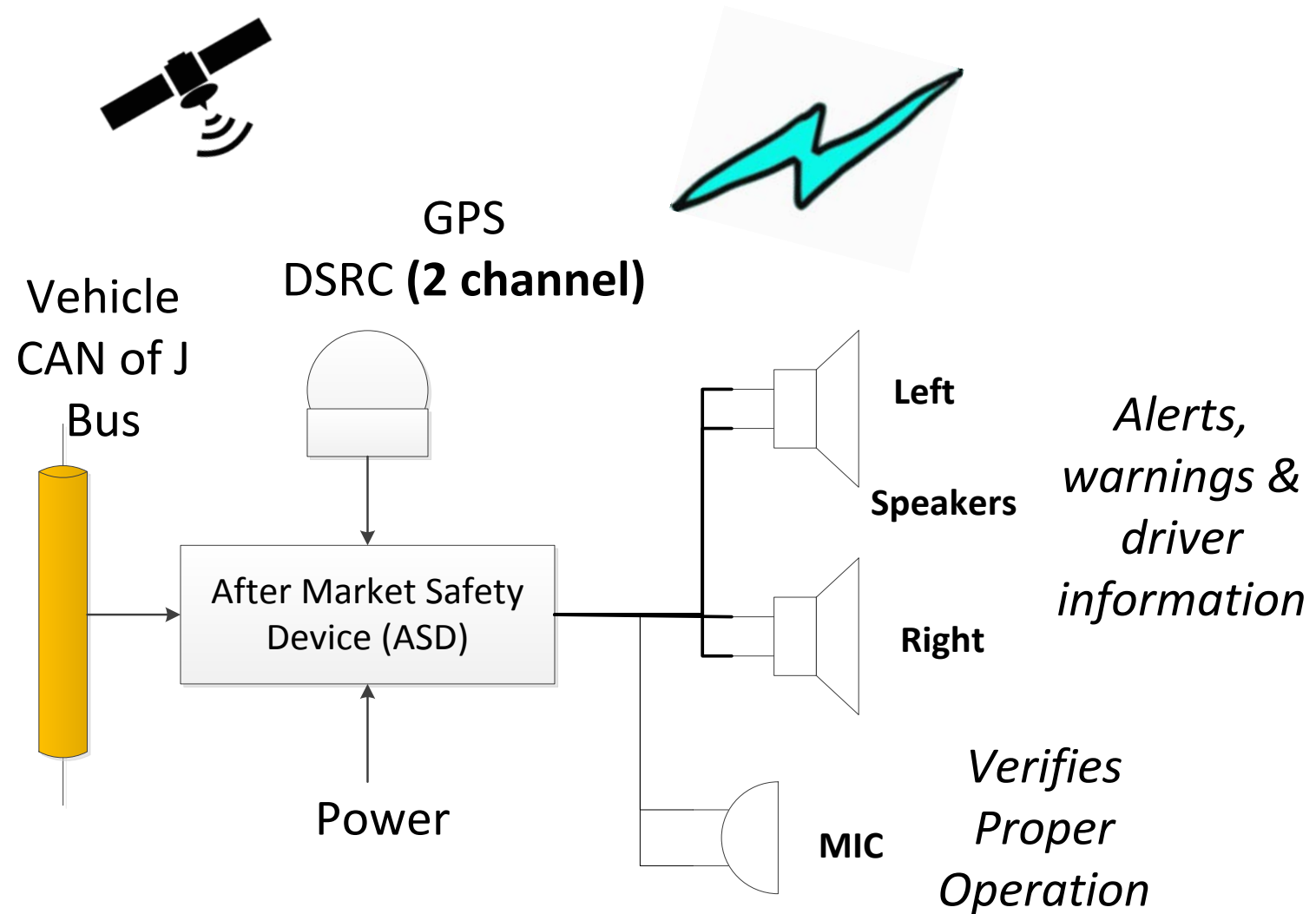


Source: NYCDOT

# AFTERMARKET SAFETY DEVICE FOR NYC



- Audio output only
  - Tones based on threat
  - Words based on situation
- ASD includes
  - Inertial Navigation
  - GNSS Navigation
  - Connection to Vehicle data Bus
  - Multi Channel DSRC support
  - Security Management Features





## Vehicle-to-Vehicle (V2V) Safety Applications

- |   |      |
|---|------|
| ▪ Vehicle Turning Right in Front of Bus Warning | VTRW |
| ▪ Forward Collision Warning                     | FCW  |
| ▪ Emergency Electronic Brake Light              | EEBL |
| ▪ Blind Spot Warning                            | BSW  |
| ▪ Lane Change Warning/Assist                    | LCA  |
| ▪ Intersection Movement Assist                  | IMA  |

*V2V applications based on **existing demonstrations and prior developments and documentation***

# SAFETY APPLICATIONS - CONTINUED



## Vehicle-to-Infrastructure (V2I) Safety Applications

- Red Light Violation Warning
  - Speed **Compliance**
  - Curve Speed **Compliance**
  - Speed **Compliance**/Work Zone
  - Oversize Vehicle **Compliance**
    - Prohibited Facilities (Parkways)
    - Over Height
  - Emergency Communications and Evacuation Information (*Traveler information*)
- RLVW
- Tailored for New York City  
- Modified from the generic versions

*V2I applications based on existing demonstrations and/or modifications to prior developments and documentation*

# OTHER APPLICATIONS



## Other Applications

- Mobile [[Visually Impaired](#)] Ped Signal System PED-SIG
- Pedestrian in Signalized Intersection Warning PEDINXWALK
- CV Data for Intelligent Traffic Signal System I-SIGCVDAT *Roadway segment travel times*

## Operations, Maintenance, and Performance Analysis

- RF Monitoring RFMON
  - OTA Firmware Update FRMWUPD
  - Parameter Up/Down Loading PARMLD
  - Traffic data collection TDC
  - *Event History Recording* EVTRECORD
  - *Event History Up Load* EVTCOLLECT
- } *To Evaluate the benefits*

# THE NYC APPROACH



- Focus on “proven” **Safety Applications** - **Prior R&D** has shown the benefits:
  - Pilot Deployment will evaluate the benefits on a much larger scale – dense urban situation
- **Leverage “existing” safety applications** (demonstrated)
  - *Manage (Tune)* the CV applications for NYC
  - Adjust operation for the congested traffic environment of NYC
- **Modify several existing applications** to encourage speed **compliance**
  - Note that the City reduced city-wide speed from 30 MPH to 25 MPH
- **Leverage existing** standards, infrastructure, and knowledge base
- Advance the state of the art:
  - *Develop operations and maintenance applications*
  - *Develop data collection applications [for benefits analysis]*
  - *Develop benefit evaluation applications*

# CHALLENGES - *EVERYWHERE*



- **Stakeholder privacy** concerns – while still collecting meaningful statistics
- Stakeholder requirements to avoid **distracting “cockpit”** displays
- **Density** of Roadside **DSRC** Transponders *DSRC – Nominal 300M - Channel Assignments & Xmit Power*
  - ~76 M for short blocks
  - ~200 M for the long blocks (between avenues)
- **Location Accuracy** – Urban Canyons (*both relative V2V and absolute V2I*)
  - Tests, trials, and consideration of alternative sources
- **Bandwidth limitations** of our wireless backhaul – *it is IPV4 only*
- Ongoing **maintenance and support** (in-vehicle and infrastructure) of the large scale deployment (8,000+ Vehicles and >350 RSUs)
- Security for all applications & DSRC Over-the-air (OTA) certificate distribution
- OTA [DSRC] data collection – bandwidth limited
- OTA [DSRC] software updates
- OTA [DSRC] parameter management

**ONLY DSRC  
Communications!**

# CHALLENGES WITH THE DENSE URBAN ENVIRONMENT



# CHALLENGE: PERFORMANCE METRICS & EVALUATION METHODS WHILE PRESERVING PRIVACY



*Safety Needs  
(ConOps)*

*Safety  
applications*

*Developed  
Questions for  
Evaluation*

*Performance  
Measurement  
Metrics ~47*

**Reduce Vehicle to Vehicle Crashes**

**V2V & V2I Safety Applications  
for Crash Avoidance**

- Does number of crashes decrease?
- Does number and severity of red light violations decrease?
- Does number of bus / right turn vehicle crashes decrease?

- Fatality crash counts
- Injury crash counts
- Property damage only crash counts
- Time to Collision
- Red light violation counts
- Red light violation crash counts
- Driver actions and/or impact of actions when they receive alerts
- Bus & right turn related crash counts
- Number of warnings generated
- Right-turning related conflicts

## **Data collection:**

*Everything that “occurred” immediately before and after the alert*

# DEPLOYMENT APPROACH



- **Turn-key ASD and RSU equipment procurement**
- **Multiple stage delivery**
  - Prototypes install/test Hardware/software/DSRC
  - Award to 2 ASD Bidders (~1/2 each) and 1 RSU Bidder
  - Production delivery after proof of prototypes
- **Concept: Verify the hardware & software platform early**
  - **Use OTA updates (firmware, parameters) to expand the applications**
- **The limiting factor – Installation time for 8000 vehicles!**
- **Expect Bid to be out in March 2017!**

# Our TEAM



## Stakeholders Fleet Owners and Users



## Project Team



SECURITY  
INNOVATION

CAMBRIDGE  
SYSTEMATICS



KLD



University  
Transportation  
Research Center

# WHERE ARE WE NOW ?



- Phase 2 – 20 Month Deployment
  - Started September 1, 2016
  - Official Kick Off September 23, 2016
  - Twenty (20) Months **(14 left!)**
    - **Developing architecture, data management plan, detailed designs, procurement documents, etc.**
  - Phase 3 Evaluation
    - Starts April 2018

*The Project Teams are sharing ideas, challenges, workshops, and the NY team is aggressively participating in the standards development program!*



# Connected Vehicle Pilot in Wyoming – Managing a Busy Freight Corridor under all Weather Conditions



Wyoming DOT

Ali Ragan, Wyoming Department of Transportation

# Wyoming's I-80 Corridor

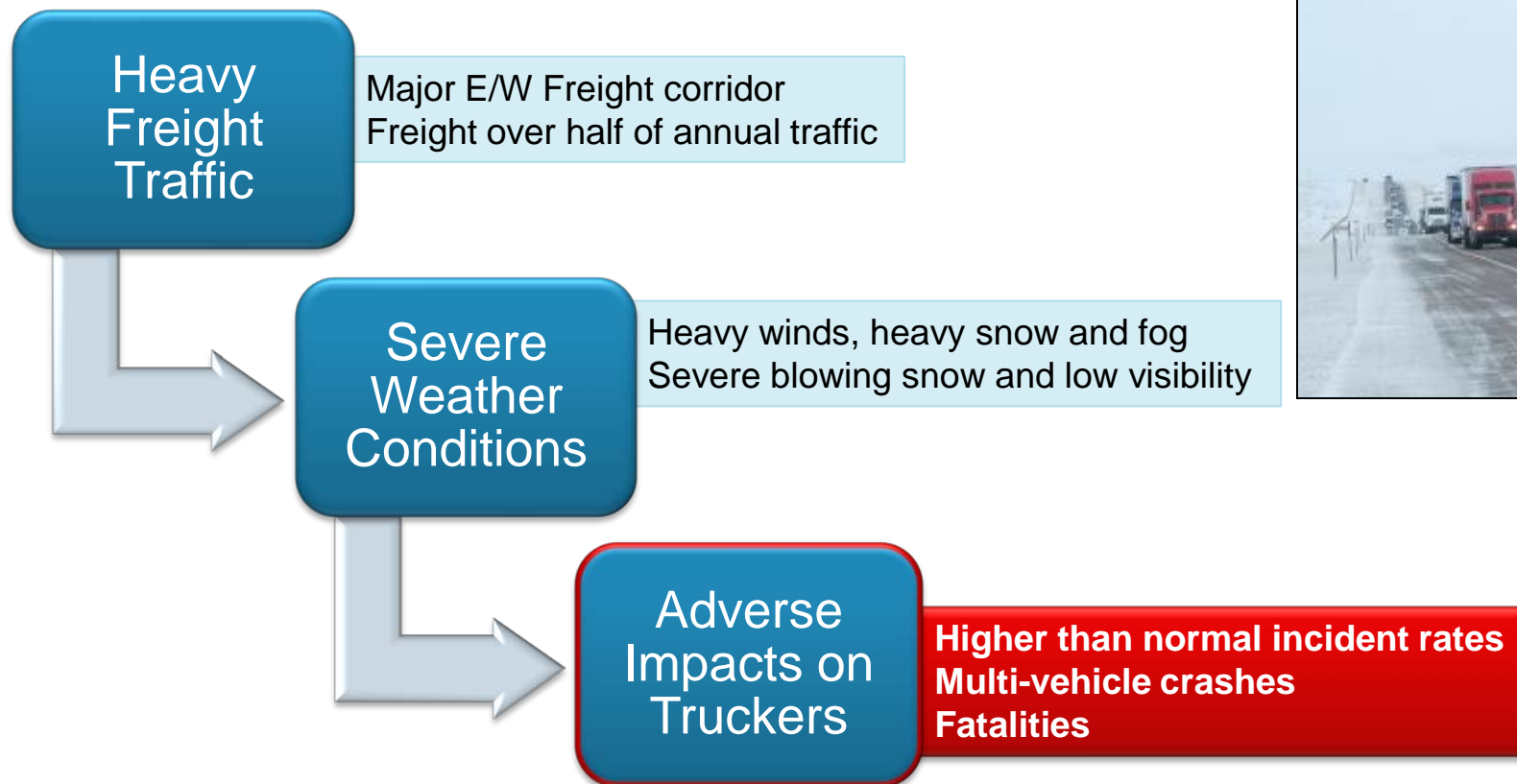


## Environmental Overview

- Project area: 402 miles from the border with Utah to the border with Nebraska
- Entire elevation higher than 6,000 feet; highest point 8,640 feet
  - Donner Pass, Calif.: 7,057 feet
  - Parley Summit, Utah: 7,120 feet



# Wyoming's I-80 Corridor



Source: WYDOT (Dec 17, 2015)



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# Wyoming's I-80 Corridor



## What's Been Done?

Variable Speed Limits

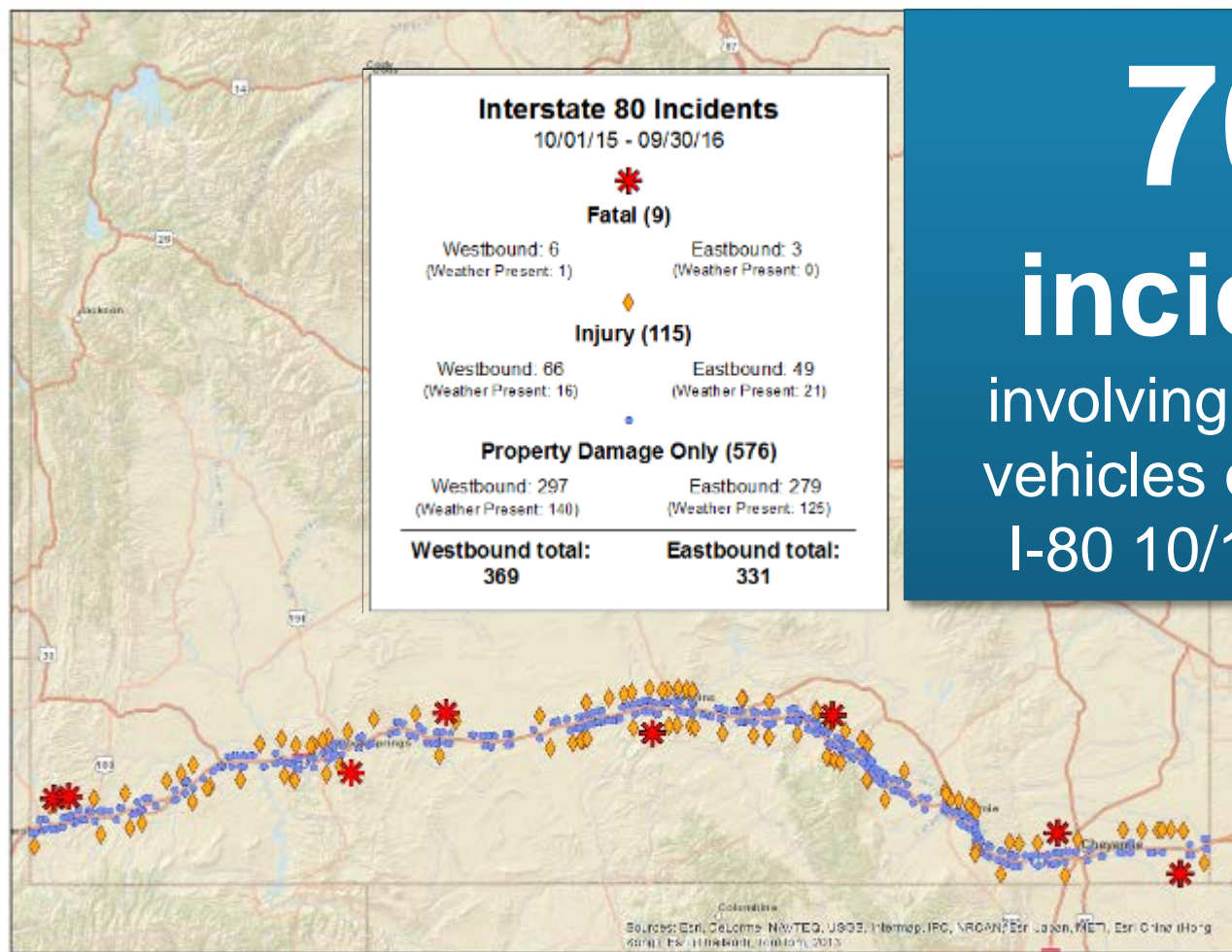
Closures to Light, High Profile-Vehicles when wind gusts top 60 mph

More efficient road condition updating





# Scope of the problem



**700**  
**incidents**  
involving commercial  
vehicles occurred on  
I-80 10/15 to 09/16

1,600+ crashes

1,923 vehicles

\$865.3M

Societal Impact



**WYDOT** | **CONNECTED  
VEHICLE PILOT**

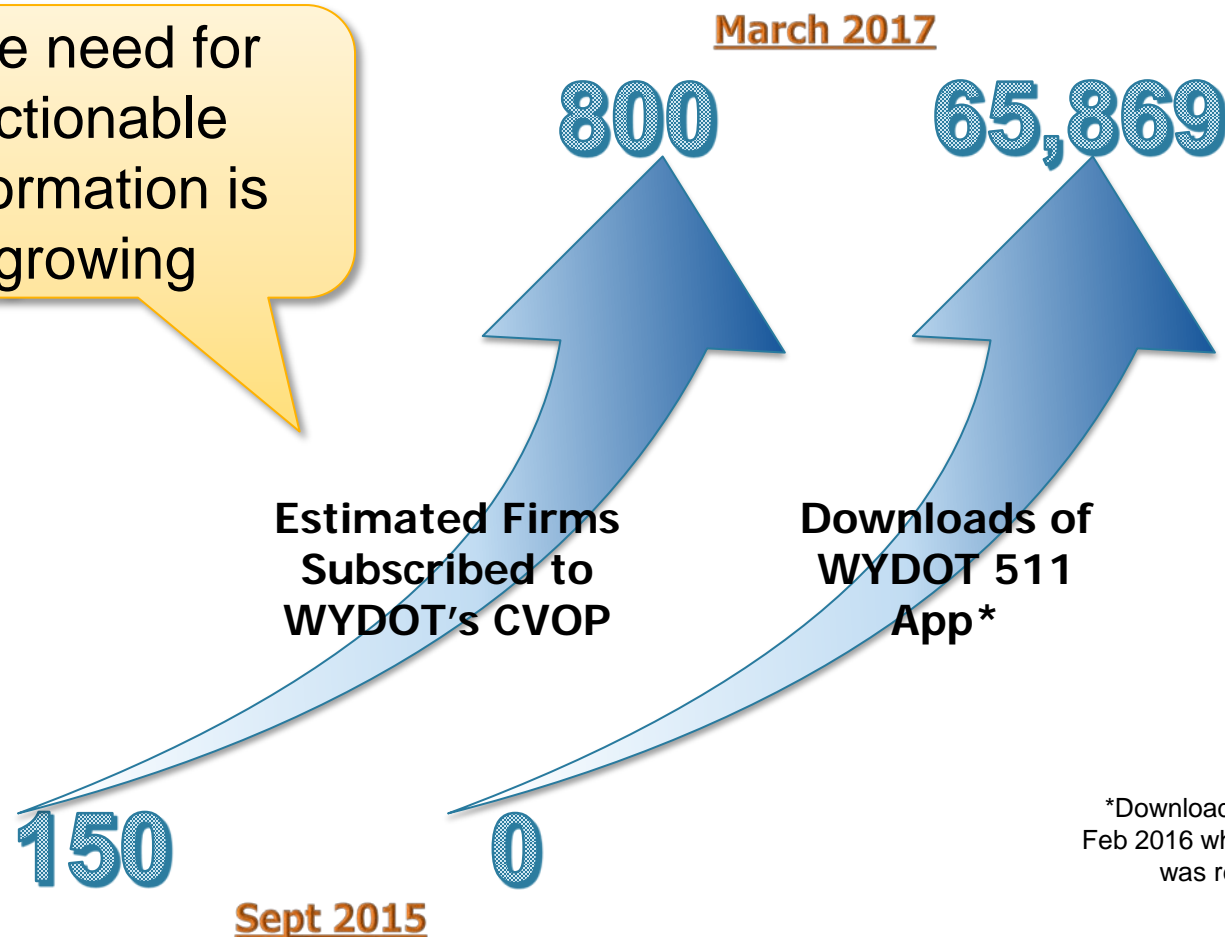


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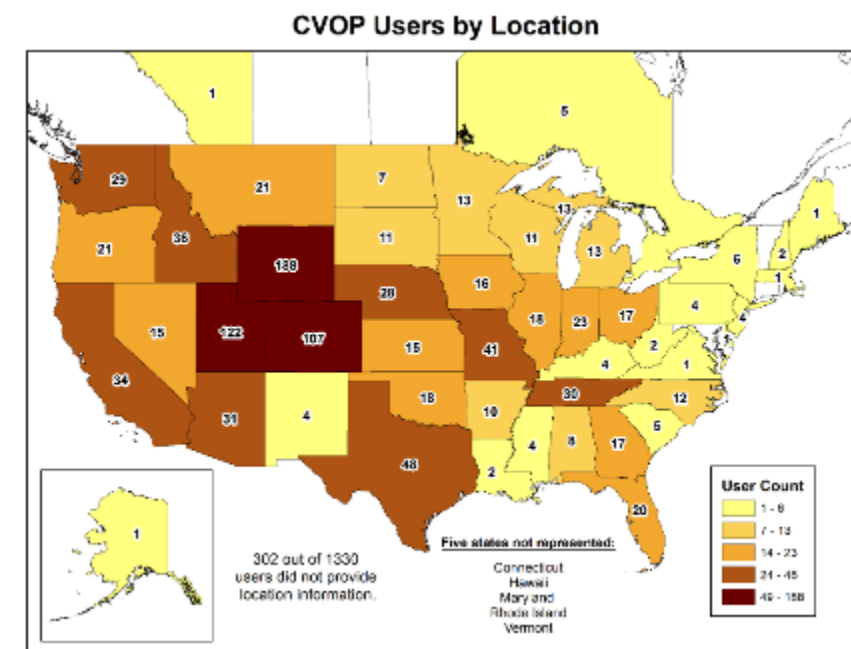
# I-80 Users Need Actionable Road Weather Information



The need for actionable information is growing



## WYDOT's Commercial Vehicle Operator Portal (CVOP)

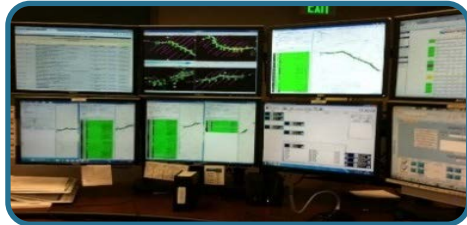


# Pilot Objectives



## Road Weather Condition Input

1. Improve road weather condition reports received into the TMC



## TMC Information Dissemination

1. Improve ability of the TMC to generate wide area alerts and advisories
2. Efficiently manage closures, restrictions and speed limits
3. Effectively disseminate and receive messages from TMC to en-route vehicles
4. Improve information to commercial vehicle fleet managers



## Vehicle/Roadside Alerts & Advisories

1. Effectively transmit and receive V2V messages to reduce incidents and their severity
2. Enhance emergency notifications of a crash



## Outcomes

1. Improve speed adherence and reduce speed variation
2. Reduce vehicle crashes

# Pilot Elements



## CV Environment

75 Roadside Units on I-80

400 Vehicles with DSRC Connectivity



## V2V Applications

Forward Collision Warning

Distress Notification

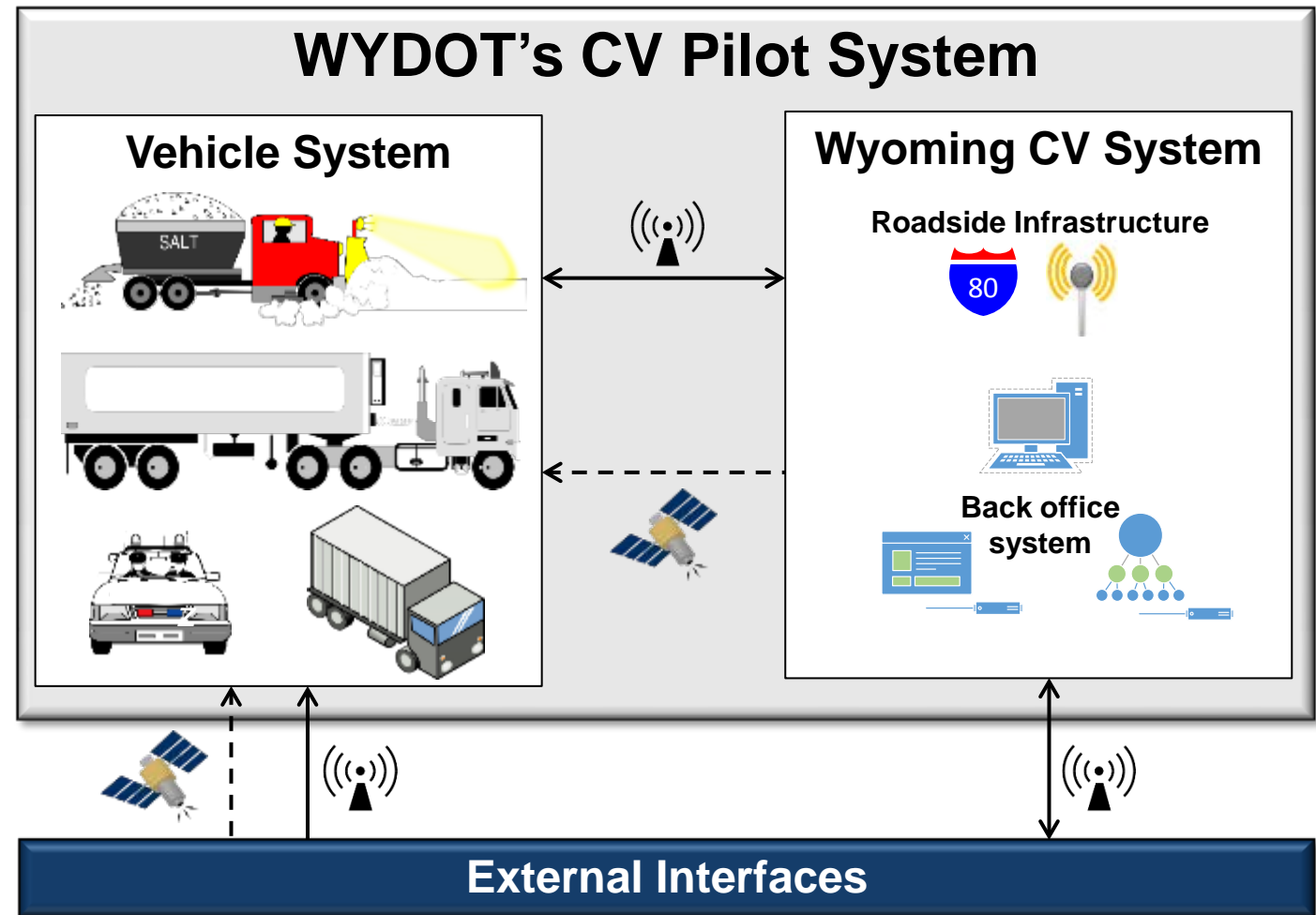


## V2I Applications

Situational Awareness

Spot Weather

Work Zone Warning



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# On-Board Applications



The pilot will develop five on-board applications that will provide road condition information to the drivers of equipped vehicles.

*Forward Collision Warning (FCW)*

*Infrastructure-to-Vehicle (I2V) Situational Awareness (SA)*

*Work Zone Warning (WZW)*

*Spot Weather Impact Warning (SWIW)*

*Distress Notification (DN)*



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# Vehicle System



All vehicles that are part of the vehicle system will have:

- Ability to share information via DSRC with connected devices (vehicles and RSUs)
- Ability to broadcast Basic Safety Message Part I
- Ability to receive Traveler Information Messages (TIM)
- Human-Machine Interface (HMI) to communicate alerts and advisories to driver



WYDOT | CONNECTED VEHICLE PILOT

## Vehicle Sub-Systems

1. WYDOT Fleets
2. Integrated Trucks
3. Retrofit Vehicles
4. Basic Vehicles

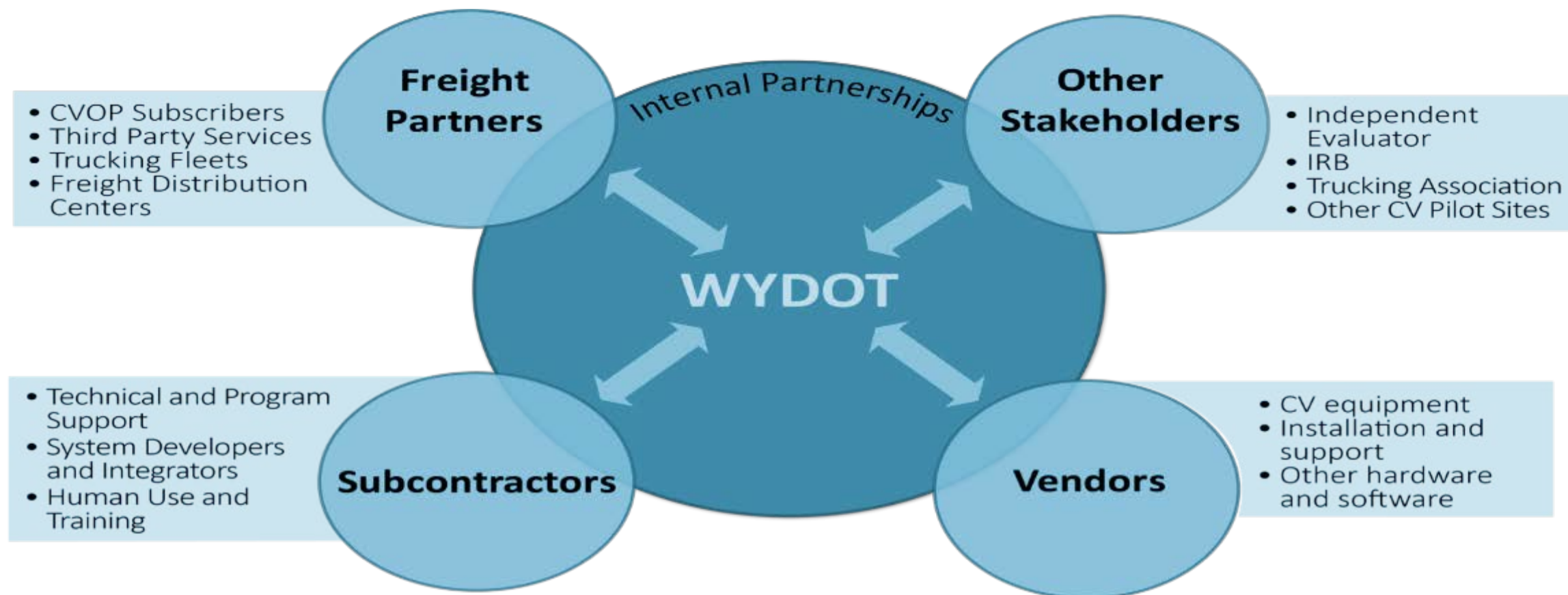
## On-board Vehicle Technologies

- OBU with DSRC only
- OBU with DSRC and Satellite Receiver
- Human Machine Interface
- CAN Bus Integration (selected vehicles)
- Environmental Sensors (selected vehicles)



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# CV Pilot Partnership





# Next Steps and Activities

Third-party data feed Spring 2017

Install roadside equipment and in-vehicle systems on WYDOT fleets  
Spring/Summer 2017


System operation and testing Winter 2017/2018

Install equipment on private vehicles Springs/Summer 2018

System operation Winter 2018/2019



# Connected Vehicle Pilot in Tampa, Florida – Managing Safety and Mobility Impacts in Integrated Expressway/Surface Street Networks



**Tampa (THEA)**  
Tampa Hillsborough  
Expressway Authority

Bob Frey, Tampa Hillsborough Expressway Authority

# TAMPA DEPLOYMENT AREA



# FOCUSED PILOT DEPLOYMENT AREA



# CV APPLICATIONS TO BE DEPLOYED



Application	Description	Use Case
Curve Speed Warning	Alerts driver approaching curve with speed safety warning	1
Emergency Electronic Brake Light (EEBL)	Enables broadcast to surrounding vehicles of severe braking	1
Forward Collision Warning (FCW)	Warns driver of impending collision ahead in same lane	1,3
Intersection Movement Assist (IMA)	Indicates unsafe (i.e., wrong way) entry into an intersection	2
Pedestrian in a Signalized Crosswalk (PED-X)	Alerts vehicle to the presence of pedestrian in a crosswalk	2,4,6
Pedestrian Mobility (PED-SIG)	Gives pedestrians priority with signal phase and timing (PED-SIG)	2,4,6
Intelligent Traffic Signal System (I-SIG)	Adjusts signal timing for optimal flow along with PED-SIG and TSP	1,2,6
Vehicle Data for Traffic Operations (VDTO)	Uses vehicles as probes to detect potential incidents, (also called Probe-enabled Data Monitoring or PeDM)	6
Transit Signal Priority (TSP)	Allows transit vehicle to request and receive priority at a traffic signal	4
Vehicle Turning Right in Front of a Transit Vehicle (VTRFTV)	Alerts transit vehicle driver that a car is attempting to turn right in front of the transit vehicle	5
Red Light Violation Warning (RLVW)	Warns driver of potential of red light violation	2



# EQUIPMENT: BY THE NUMBERS

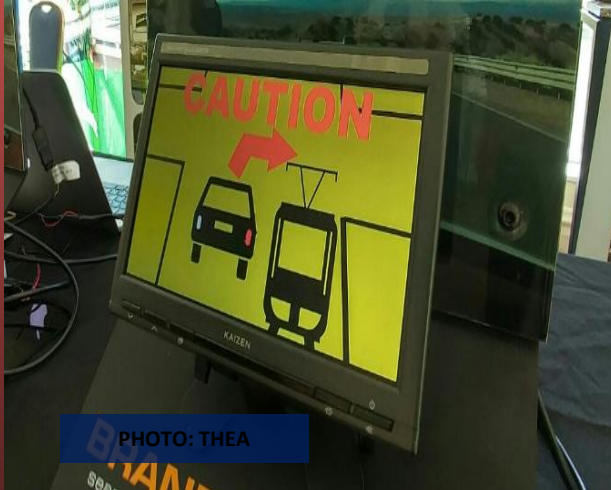


PHOTO: THEA

**1,620**

**On-Board Units  
(OBUs)**

A rear view mirror for  
passenger vehicles and tablet  
display for transit vehicles



PHOTO: NPR

**500+**

**Pedestrian  
smartphones (Android  
devices only)**



PHOTO: SIEMENS

**40**

**Road Side Units  
(RSUs)**

Mounted on existing structures  
throughout the deployment  
area



# MORNING BACKUP



**Forward Collision  
Warning (FCW)**

**Emergency  
Electronic Brake  
Light (EEBL)**

**End of Ramp  
Deceleration  
Warning (ERDW)**

# WRONG-WAY DRIVERS



**Wrong-way  
Entry**

**Intelligent Signal  
System (I-SIG)**

**Intersection  
Movement  
Assist (IMA)**



PHOTO: TAMPA HILLSBOROUGH EXPRESSWAY AUTHORITY (THEA)

# PEDESTRIAN SAFETY



**Mobile Accessible  
Pedestrian Signal  
System (PED-SIG)**

**Pedestrian in a  
Crosswalk Vehicle  
Warning (PED-X)**

**FCW**

**IMA**



# TRANSIT SIGNAL PRIORITY



**I-SIG**

**Transit Signal  
Priority (TSP)**

**IMA**

# STREETCAR CONFLICTS



**Vehicle Turning  
Right in Front of  
Transit Vehicle  
(VTRFTV)**

**I-SIG**

**PED-SIG**

**PED-X**



# TRAFFIC PROGRESSION

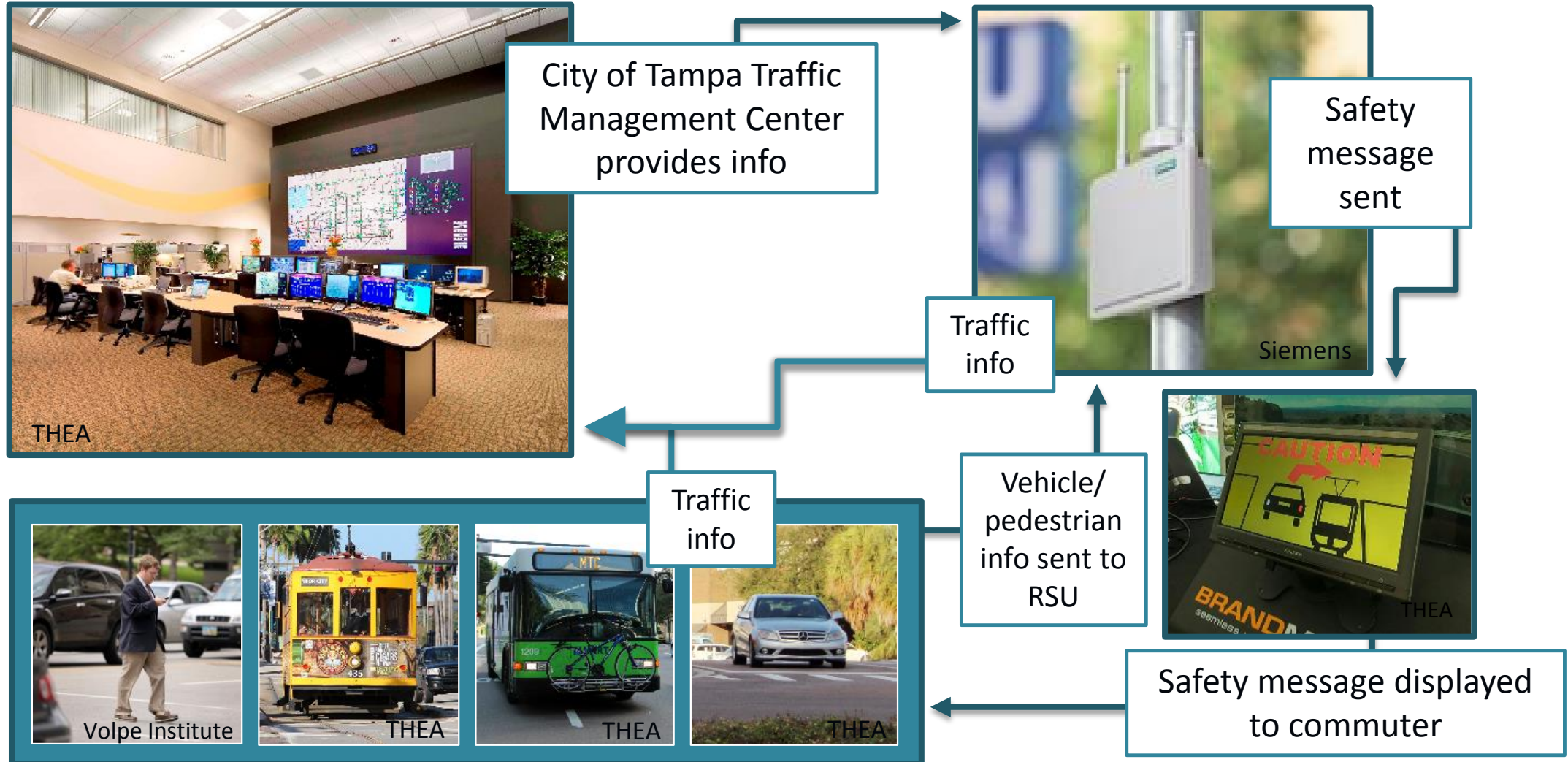


**Probe Data  
Enabled Traffic  
Monitoring  
(PDETM)**

**I-SIG**

**IMA**

# INFORMATION FLOW



# RSU PHOTOS



Source: Siemens



# HMI PHOTO



Mirror display uses sticker to depict location and concept of warning.  
Actual image is still in development

# How Much Data?



70 billion connected devices (2050)

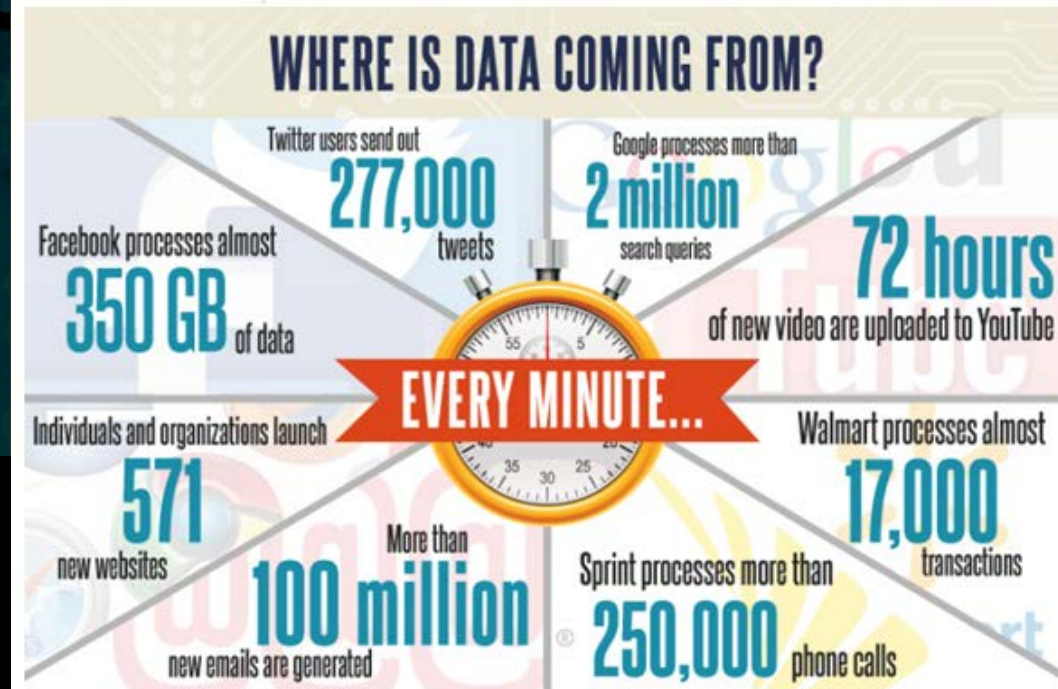
2.8 trillion sensors (2019)

Autonomous Vehicles (L2)

- 80+ processors
- 200+ sensors
- 100M+ lines of code (GM)

**2,500,000,000,000,000,000**

2.5 Quintillion bytes **EVERY DAY**



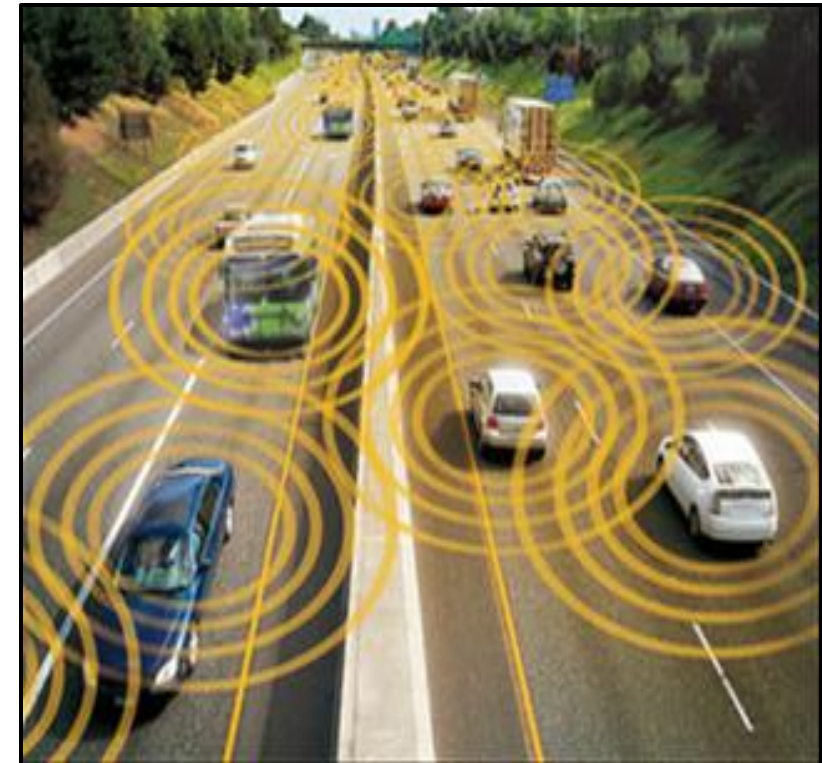
# WHAT IS IMPORTANT TO ROAD OPERATORS? DAY TO DAY OPERATIONS



# QUANTIFIABLE BENEFITS



- **SAFETY:** Connected vehicle technology could affect **more than 80% of vehicular crash scenarios** involving unimpaired drivers
- Improved mobility
- Reduce environmental impact
- Assist with toll interoperability
- Economic Impacts
  - Reduction in insurance rates
  - Realize fuel & maintenance savings – Inflation Fighter
  - Recoup productivity currently lost to long or erratic commutes



# CONNECTED VEHICLES: MOVING CV SOLUTIONS INTO THE PLANNING PROCESS



- Selmon East Capacity Improvements (Sample Project)
  - Additional lane in each direction for 16 miles - \$200 million
  - Selmon East Lane Harmonization
    - Bridge Improvements (3 Bridges) - \$75 million
    - Speed Harmonization - \$50 million
- Potential Savings - \$75 million or 6-7 years delay of capacity improvements
- If nothing else,  
it is worth investigating...



# FOR MORE INFORMATION...



## Robert M. Frey, AICP

Planning Director, Tampa Hillsborough Expressway Authority  
Project Manager, Tampa Connected Vehicle Pilot Deployment Program

1104 E. Twiggs St.

Ste. 300

Tampa, FL 33602

(813) 272-6740

[bobf@tampa-xway.com](mailto:bobf@tampa-xway.com)

## Steve Novosad

HNTB

Systems Engineering Lead, Tampa Connected Vehicle Pilot

201 N. Franklin St.

Ste. 1200

Tampa, FL 33602

[snovosad@hntb.com](mailto:snovosad@hntb.com)



[TampaCVpilot.com](http://TampaCVpilot.com)



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# CONNECTED VEHICLE PILOT Deployment Program



## Panel Discussion and Q&A

Egan Smith, Managing Director, ITS JPO, USDOT

# STAY CONNECTED



## Visit USDOT Exhibition Booth for More Information

- USDOT Booth No: **409** (Near NASA)
  - March 12-14, 10:00 am to 6:00 pm
  - March 15, 10:00 am to 2:00 pm

## Join us for the *Getting Ready for Deployment* Series

**Website:** <http://www.its.dot.gov/pilots>

- Discover more about the CV Pilot Sites
- Learn the Essential Steps to CV Deployment
- Engage in Technical Discussion

## Contact for CV Pilots Program:

Kate Hartman, Program Manager

[Kate.hartman@dot.gov](mailto:Kate.hartman@dot.gov)

## Contact for Pilot Sites:

- Kate Hartman, WYDOT Site AOR  
[Kate.Hartman@dot.gov](mailto:Kate.Hartman@dot.gov)
- Jonathan Walker, NYCDOT Site AOR  
[Jonathan.b.Walker@dot.gov](mailto:Jonathan.b.Walker@dot.gov)
- Govind Vadakpat, THEA Site AOR  
[G.Vadakpat@dot.gov](mailto:G.Vadakpat@dot.gov)

